

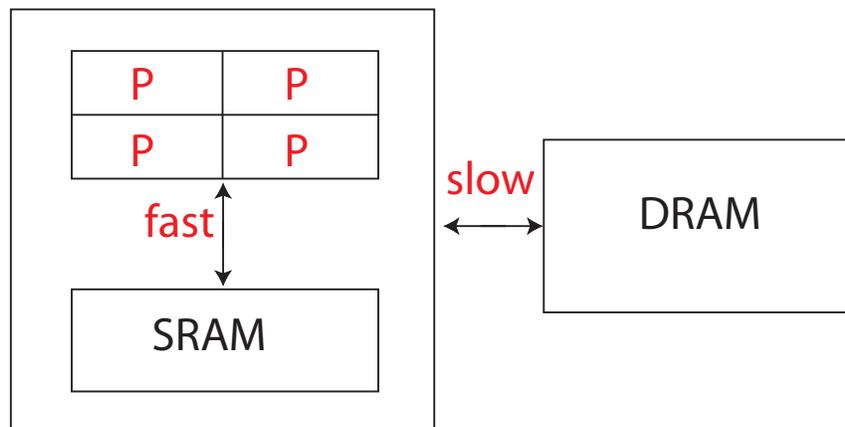
## Lecture 24: Parallel Processor Architecture & Algorithms

### Processor Architecture

Computer architecture has evolved:

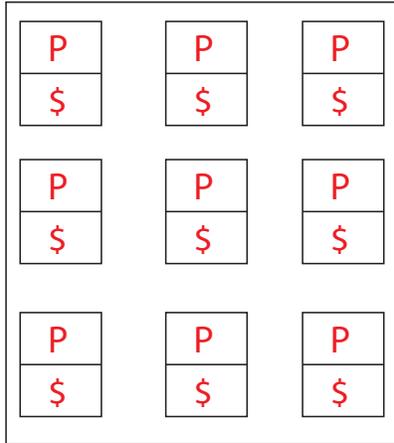
- Intel 8086 (1981): 5 MHz (used in first IBM PC)
- Intel 80486 (1989): 25 MHz (became i486 because of a court ruling that prohibits the trademarking of numbers)
- Pentium (1993): 66 MHz
- Pentium 4 (2000): 1.5 GHz (deep  $\approx$  30-stage pipeline)
- Pentium D (2005): 3.2 GHz (and then the clock speed stopped increasing)
- Quadcore Xeon (2008): 3 GHz (increasing number of cores on chip is key to performance scaling)

Processors need data to compute on:



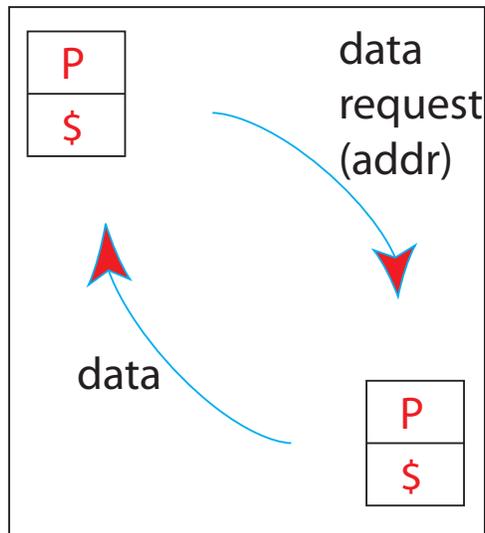
**Problem:** SRAM cannot support more than  $\approx$  4 memory requests in parallel.

§: cache P: processor



Most of the time program running on the processor accesses local or “cache” memory

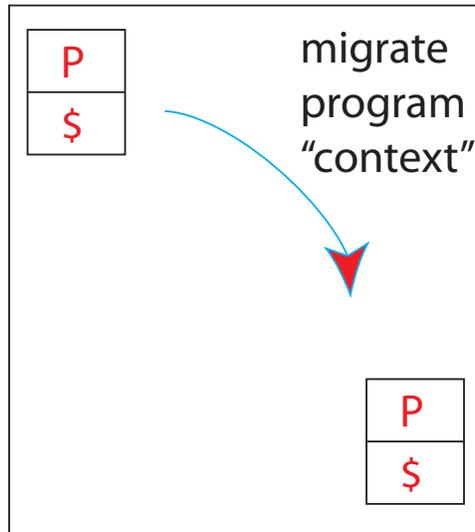
Every once in a while, it accesses remote memory:



Round-trip required to obtain data

## Research Idea: Execution Migration

When program running on a processor needs to access cache memory of another processor, it migrates its “context” to the remote processor and executes there:



One-way trip for data access

Context = ProgramCounter + RegisterFile + ... (can be larger than data to be accessed)

fewKbits

Assume we know or can predict the access pattern of a program

$m_1, m_2, \dots, m_N$  (memory addresses)

$p(m_1), p(m_2), \dots, p(m_N)$  (processor caches for each  $m_i$ )

### Example

$p_1 p_2 p_2 p_1 p_1 p_3 p_2$

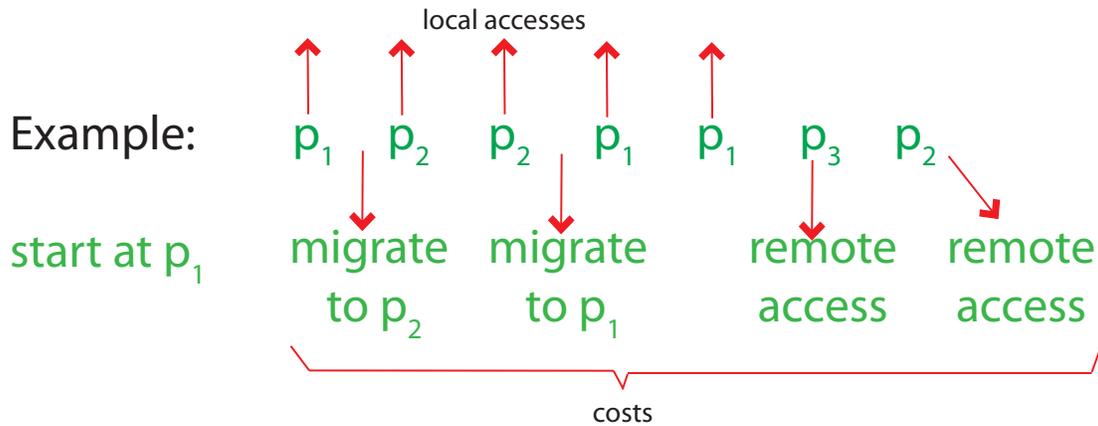
$\text{cost}_{\text{mig}}(s, d) = \text{distance}(s, d) + L$  ← load latency  $L$  is a function of context size

$\text{cost}_{\text{access}}(s, d) = 2 * \text{distance}(s, d)$

if  $s == d$ , costs are defined to be 0

**Problem**

Decide when to migrate to minimize total memory cost of trace For example:



What can we use to solve this problem?

Dynamic Programming!

**Dynamic Programming Solution**

Program at  $p$ , initially, number of processors =  $Q$

**Subproblems?**

Define  $DP(k, p_i)$  as cost of optimal solution for the prefix  $m_1, \dots, m_k$  of memory accesses when program starts at  $p_1$  and ends up at  $p_i$ .

$$DP(k+1, p_j) = \begin{cases} DP(k, p_j) + \text{cost}_{\text{access}}(p_j, p(m_{k+1})) & \text{if } p_j \neq p(m_{k+1}) \\ \text{MIN}_{i=1}^Q (DP(k, p_i) + \text{cost}_{\text{mig}}(p_i, p_j)) & \text{if } p_j = p(m_{k+1}) \end{cases}$$

**Complexity?**

$$O(\underbrace{N \cdot Q}_{\text{no. of subproblems}} \cdot \underbrace{Q}_{\text{cost per subproblem}}) = O(NQ^2)$$

My research group is building a 128-processor Execution Migration Machine that uses a migration predictor based on this analysis.

## Lecture 24: Research Areas and Beyond 6.006

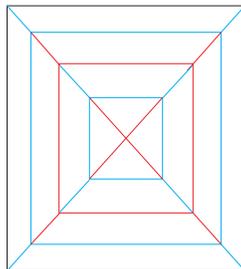
### Erik's Main Research Areas

- computational geometry [6.850]
  - geometric folding algorithms [6.849]
  - self-assembly
- data structures [6.851]
- graph algorithms [6.899]
- recreational algorithms [SP.268]
- algorithmic sculpture

### Geometric Folding Algorithms: [6.849], Videos Online

Two aspects: design and foldability

- design: algorithms to fold any polyhedral surface from a square of paper [Demaine, Demaine, Mitchell (2000); Demaine & Tachi (2011)]
  - bicolor paper  $\implies$  can 2-color faces
  - OPEN: how to best optimize “scale-factor”
  - e.g. best  $n \times n$  checkerboard folding — recently improved from  $\approx n/2 \rightarrow \approx n/4$
- foldability: given a crease pattern, can you fold it flat
  - NP-complete in general Bern & Hayes (1996)
  - OPEN:  $m \times n$  map with creases specified as mountain/valley [Edmonds (1997)]
  - just solved:  $2 \times n$  Demaine, Liu, Morgan (2011)
  - hyperbolic paraboloid [Bauhaus (1929)] doesn't exist [Demaine, Demaine, Hart, Price, Tachi (2009)]



- understanding circular creases
- any straight-line graph can be made by folding flat & one straight cut [Demaine, Demaine, Lubiw (1998); Bern, Demaine, Eppstein, Hayes (1999)]

## Self-Assembly

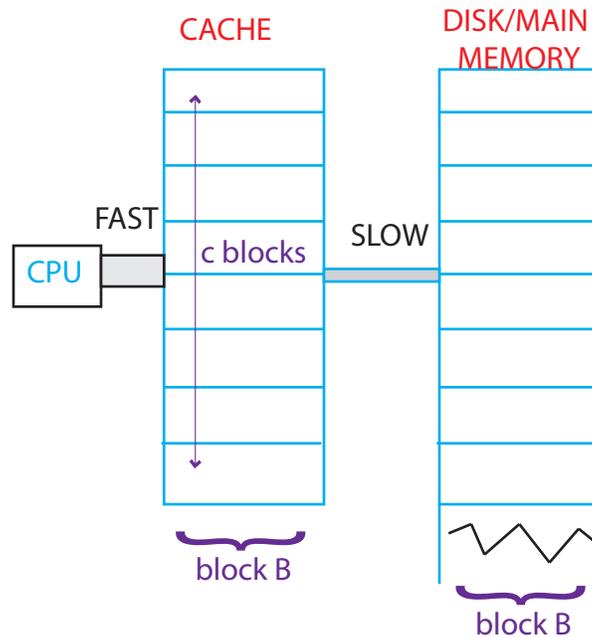
Geometric model of computation

- glue e.g. DNA strands, each pair has strength
- square tiles with glue on each side
- Brownian motion: tiles/constructions — stick together if  $\sum$ glue strengths  $\geq$  temperature
- can build  $n \times n$  square using  $O\left(\frac{\lg n}{\lg \lg n}\right)$  tiles [Rothemund & Winfree 2000] or using  $O(1)$  tiles &  $O(\lg n)$  “stages” algorithmic steps by the bioengineer [Demaine, Demaine, Fekete, Ishaque, Rafalin, Schweller, Souvaine (2007)]
- can replicate  $\infty$  copies of given unknown shape using  $O(1)$  tiles and  $O(1)$  stages [Abel, Benbernou, Damian, Demaine, Flatland, Kominers, Schweller (2010)]

## Data Structures: [6.851], Videos Next Semester

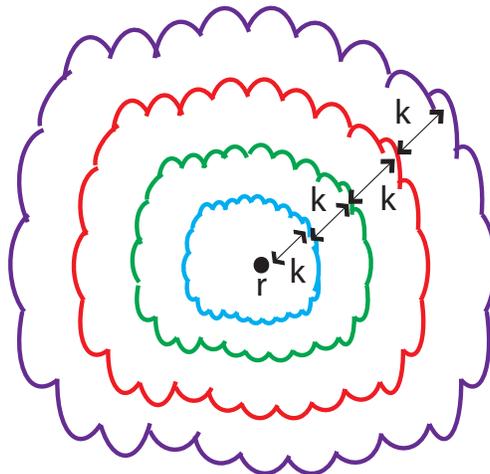
There are 2 main categories of data structures

- Integer data structures: store  $n$  integers in  $\{0, 1, \dots, u - 1\}$  subject to insert, delete, predecessor, successor (on word RAM)
  - hashing does exact search in  $O(1)$
  - AVL trees do all in  $O(\lg n)$
  - $O(\lg \lg u)$ /op van Emde Boas
  - $O\left(\frac{\lg n}{\lg \lg u}\right)$ /op fusion trees: Fredman & Willard
  - $O\left(\sqrt{\frac{\lg n}{\lg \lg n}}\right)$ /op min of above
- Cache-efficient data structures
  - memory transfers happen in blocks (from cache to disk/main memory)
  - searching takes  $\Theta(\log_B N)$  transfers (vs.  $\lg n$ )
  - sorting takes  $\Theta\left(\frac{N}{B} \log_C \frac{N}{B}\right)$  transfers
  - possible even if you don't know B & C !



### (Almost) Planar Graphs: [6.889], Videos Online

- Dijkstra in  $O(n)$  time [Henzinger, Klein, Rao, Subramanian (1997)]
- Bellman-Ford in  $O\left(\frac{n \lg^2 n}{\lg \lg n}\right)$  time [Mozes & Wolff-Nilson (2010)]
- Many problems NP-hard, even on planar graphs. But can find a solution within  $1 + \epsilon$



factor of optimal, for any  $\epsilon$  [Baker 1994 & Others]:

- run BFS from any root vertex  $r$
- delete every  $k$  layers
- for many problems, solution messed up by only  $1 + \frac{1}{k}$  factor ( $\implies k = \frac{1}{\varepsilon}$ )
- connected components of remaining graph have  $< k$  layers. Can solve via DP typically in  $\approx 2^k \cdot n$  time

### Recreational Algorithms

- many algorithms and complexities of games [some in SP.268 and our book *Games, Puzzles & Computation* (2009)]
- $n \times n \times n$  Rubik's Cube diameter is  $\Theta \frac{n^2}{\lg n}$  [Demaine, Demaine, Eisenstat, Lubiw, Winslow (2011)]
- Tetris is NP-complete [Breukelaar, Demaine, Hohenberger, Hoogeboom, Kusters, Liben-Nowell (2004)]
- balloon twisting any polyhedron [Demaine, Demaine, Hart (2008)]
- algorithmic magic tricks

**Algorithms Classes at MIT: (post 6.006)**

- 6.046: Intermediate Algorithms (more advanced algorithms & analysis, less coding)
- 6.047: Computational Biology (genomes, phylogeny, etc.)
- 6.854: Advanced Algorithms (intense survey of whole field)
- 6.850: Geometric Computing (working with points, lines, polygons, meshes, ...)
- 6.849: Geometric Folding Algorithms origami, robot arms, protein folding, ...
- 6.851: Advanced Data Structures (sublogarithmic performance)
- 6.852: Distributed Algorithms (reaching consensus in a network with faults)
- 6.853: Algorithmic Game Theory (Nash equilibria, auction mechanism design, ...)
- 6.855: Network Optimization (optimization in graph: beyond shortest paths )
- 6.856: Randomized Algorithms (how randomness makes algorithms simpler & faster)
- 6.857: Network and Computer Security (cryptography)

**Other Theory Classes:**

- 6.045: Automata, Computability, & Complexity
- 6.840: Theory of Computing
- 6.841: Advanced Complexity Theory
- 6.842: Randomness & Computation
- 6.845: Quantum Complexity Theory
- 6.440: Essential Coding Theory
- 6.441: Information Theory

# Top 10 Uses of 6.006 Cushions

10. Sit on it: guaranteed inspiration in constant time  
(bring it to the final exam)
9. Frisbee (after cutting it into a circle)\*
8. Sell as a limited-edition collectible on eBay  
(they'll probably never be made again—at least \$5)
7. Put two back-to-back to remove branding\*  
(so no one will ever know you took this class)
6. Holiday conversation starter... and stopper  
(we don't recommend re-gifting)
5. Asymptotically optimal acoustic paneling  
(for practicing piano & guitar fingering DP)
4. Target practice for your next LARP\*  
(Live Action Role Playing)
3. Ten years from now, it might be all you'll  
remember about 6.006  
(maybe also this top ten list)
2. Final exam cheat sheet\*
1. *Three words:* OkCupid profile picture

MIT OpenCourseWare  
<http://ocw.mit.edu>

6.006 Introduction to Algorithms  
Fall 2011

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.